

## Math 601 Midterm 1 Solution

This is the solution sheet for Midterm 1 of Math 601. Watch out for typos/errors. Please let me know if you spot any of them.

**Question 1. (18 pts)**

Determine whether each of the following statements is true or false. You do NOT need to explain.

(a) Let  $V$  be a linear subspace of  $\mathbb{R}^n$ . We have vectors  $v_1, \dots, v_k$  and  $w_1, \dots, w_\ell$  in  $V$ . Suppose  $v_1, \dots, v_k$  are linearly independent, and  $w_1, \dots, w_\ell$  span  $V$ . Then  $k \leq \ell$ .

(b) Let  $U$  and  $W$  be subspaces of the vector space  $V$ . If  $U \subseteq W$ , then  $U + W = W$ .

(c) An  $(n \times n)$  matrix is invertible if and only if it is row equivalent to the  $(n \times n)$  identity matrix  $I_n$ .

(d) Suppose  $A$  is an  $(n \times m)$  matrix, then  $\dim \text{Im}(A) \leq n$  and  $\dim \ker(A) \leq m$ .

(e) Let  $A, B, C$  be three  $(n \times n)$  square matrices. If  $AB = AC$ , then  $B = C$ .

(f) The linear system

$$\begin{array}{rclcrcl} x & + & 10y & - & 3z & = & 3 \\ 3x & + & 4y & + & 9z & = & 1 \\ 2x & + & 5y & - & 2z & = & 8 \end{array}$$

has exactly two solutions.

**Solution:**

(a) True

(b) True

(c) True

(d) True

(e) False

(f) False (a linear system can never have precisely two solutions.)

**Question 2. (10 pts)**

A line  $L$  in  $\mathbb{R}^3$  passes through the point  $(0, 1, 0)$ . Suppose  $L$  is parallel to the plane  $x + y + z = 0$  and is orthogonal to the line

$$x = 2t, y = t + 1, z = -t.$$

Find parametric equations of the line  $L$ .

**Solution:** The direction vector of  $L$  is orthogonal to both the normal vector  $u = (1, 1, 1)$  of the plane and the direction vector  $v = (2, 1, -1)$  of the other line.

Calculate the cross product of  $u$  and  $v$ :

$$u \times v = (-2, -3, -1)$$

So we have the following parametric equations of  $L$ :

$$\begin{cases} x = -2t \\ y = 3t + 1 \\ z = -t \end{cases}$$

**Question 3. (15 pts)**

Given

$$A = \begin{bmatrix} 2 & 2 & -3 & 1 & 13 \\ 1 & 1 & 1 & 1 & -1 \\ 3 & 3 & -5 & 0 & 14 \\ 6 & 6 & -2 & 4 & 16 \end{bmatrix}$$

(a) Find a basis of  $\text{Ker}(A)$ .

**Solution:** First, use elementary row operations to get the reduced row echelon form of  $A$ .

$$\text{rref}(A) = \begin{bmatrix} 1 & 1 & 0 & 0 & -2 \\ 0 & 0 & 1 & 0 & -4 \\ 0 & 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

So all elements in  $\text{Ker}A$  are of the form

$$t \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + s \begin{bmatrix} 2 \\ 0 \\ 4 \\ -5 \\ 1 \end{bmatrix}$$

So

$$v_1 = \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, v_2 = \begin{bmatrix} 2 \\ 0 \\ 4 \\ -5 \\ 1 \end{bmatrix}$$

form a basis of the kernel.

(b) Find a basis of the row space of  $A$ .

**Solution:** The three nonzero rows in the reduced row echelon form of  $A$  form a basis of the row space of  $A$ . That is

$$u_1 = (1, 1, 1, 1, -1)$$

$$u_2 = (0, 0, -5, -1, 15)$$

$$u_3 = (0, 0, 0, 1, 5)$$

form a basis of the row space of  $A$ .

(c) Find a basis of  $\text{Im}(A)$ .

**Solution:** Use  $\text{rref}(A)$  from the part (a), we see that the 1st, 3rd and 4th columns of  $A$  form a basis of  $\text{Im}(A)$ . That is,

$$w_1 = \begin{bmatrix} 2 \\ 1 \\ 3 \\ 6 \end{bmatrix}, w_2 = \begin{bmatrix} -3 \\ 1 \\ -5 \\ -2 \end{bmatrix}, w_3 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 4 \end{bmatrix}$$

form a basis of  $\text{Im}(A)$ .

**Question 4. (10 pts)**

Let  $M_2(\mathbb{R})$  be the space of all  $(2 \times 2)$  matrices with real coefficients. The set

$$S = \left\{ \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}, \begin{pmatrix} 1 & -1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \right\}$$

is a basis of  $M_2(\mathbb{R})$ . Find the coordinates of  $A = \begin{pmatrix} 5 & 3 \\ 3 & 1 \end{pmatrix}$  with respect to the basis  $S$ .

**Solution:** We need to write

$$\begin{pmatrix} 5 & 3 \\ 3 & 1 \end{pmatrix} = a_1 \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} + a_2 \begin{pmatrix} 1 & -1 \\ 1 & 0 \end{pmatrix} + a_3 \begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix} + a_4 \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}.$$

That is, we need to solve the linear system

$$\begin{cases} a_1 + a_2 + a_3 + a_4 = 5 \\ a_1 - a_2 - a_3 = 3 \\ a_1 + a_2 = 3 \\ a_1 = 1 \end{cases}$$

Simply use back substitution. We have

$$a_1 = 1, a_2 = 2, a_3 = -4, a_4 = 6$$

So

$$[A]_S = \begin{bmatrix} 1 \\ 2 \\ -4 \\ 6 \end{bmatrix}$$

**Question 5. (10 pts)**

Determine whether  $x = \begin{bmatrix} 4 \\ 5 \\ 6 \\ -1 \end{bmatrix}$  lies in the linear span of the vectors

$$v_1 = \begin{bmatrix} 1 \\ 3 \\ 2 \\ 5 \end{bmatrix}, v_2 = \begin{bmatrix} 0 \\ 4 \\ -1 \\ 2 \end{bmatrix} \text{ and } v_3 = \begin{bmatrix} 1 \\ -2 \\ 1 \\ 3 \end{bmatrix}.$$

**Solution:** Write down the matrix

$$\left[ \begin{array}{ccc|c} 1 & 0 & 1 & 4 \\ 3 & 4 & -2 & 5 \\ 2 & -1 & 1 & 6 \\ 5 & 2 & 3 & -1 \end{array} \right]$$

by applying elementary row operations, we get

$$\left[ \begin{array}{ccc|c} 1 & 0 & 0 & 7/3 \\ 0 & 1 & 0 & 1/3 \\ 0 & 0 & 1 & 5/3 \\ 0 & 0 & 0 & 55/12 \end{array} \right]$$

This is inconsistent. So no solution. In other words,  $x$  is not in the linear span of  $v_1, v_2$  and  $v_3$ .

**Question 6. (6 pts)**

Let  $V$  be a vector space. Suppose  $F : V \rightarrow V$  is a linear transformation. Show that the kernel of  $F$  is a subspace of  $V$ .

**Solution:**

(1)  $0 \in \ker F$ , since  $F(0) = 0$ .

(2) If  $v, w \in \ker F$ , then

$$F(v + w) = F(v) + F(w) = 0 + 0 = 0.$$

So  $v + w \in \ker F$ .

(3) If  $w \in \ker F$  and  $k \in \mathbb{R}$ , then

$$F(kw) = kF(w) = k \cdot 0 = 0.$$

So  $kw \in \ker F$ .

Therefore  $\ker F$  is a subspace of  $V$ .



**Question 7. (10 pts)**

Show that  $(t - 1)$ ,  $(t + 1)$  and  $(t - 1)^2$  form a basis of  $\mathbb{P}_2(t)$ , where  $\mathbb{P}_2(t)$  is the space of all polynomials of degree  $\leq 2$ .

**Solution:** There are various ways to solve this problem.

- (1) First method: prove that  $(t - 1)$ ,  $(t + 1)$  and  $(t - 1)^2$  are linearly independent and span  $\mathbb{P}_2(t)$ .
- (2) Second method: prove that  $(t - 1)$ ,  $(t + 1)$  and  $(t - 1)^2$  are linearly independent and use the fact  $\dim \mathbb{P}_2(t) = 3$ .
- (3) third method: prove that  $(t - 1)$ ,  $(t + 1)$  and  $(t - 1)^2$  span  $\mathbb{P}_2(t)$  and use the fact  $\dim \mathbb{P}_2(t) = 3$ .

Let us use the second method. Consider a linear combination of  $(t - 1)$ ,  $(t + 1)$  and  $(t - 1)^2$  such that

$$a_1(t - 1) + a_2(t + 1) + a_3(t - 1)^2 = 0.$$

Then we want to show that  $a_1 = a_2 = a_3 = 0$  is the unique solution. This would imply that  $(t - 1)$ ,  $(t + 1)$  and  $(t - 1)^2$  are linearly independent.

Regroup the coefficients, and we have the following linear system:

$$\begin{cases} -a_1 + a_2 + a_3 = 0 \\ a_1 + a_2 - 2a_3 = 0 \\ a_3 = 0 \end{cases}$$

Solve this and indeed we have the unique solution  $a_1 = a_2 = a_3 = 0$ . So  $(t - 1)$ ,  $(t + 1)$  and  $(t - 1)^2$  are linearly independent.

Now we know that  $\dim \mathbb{P}_2(t) = 3$ . Then any 3 linearly independent vectors of  $\mathbb{P}_2(t)$  form a basis. Therefore  $(t - 1)$ ,  $(t + 1)$  and  $(t - 1)^2$  form a basis.

**Question 8. (5 pts)**

Suppose  $A$  and  $B$  are invertible ( $n \times n$ ) matrices. Then we know that  $AB$  is also invertible. Use this fact and the definition of the inverse of an invertible matrix to show that

$$(AB)^{-1} = B^{-1}A^{-1}.$$

**Solution:** Notice that

$$B^{-1}A^{-1}(AB) = B^{-1}(A^{-1}A)B = B^{-1}IB = I$$

$$(AB)B^{-1}A^{-1} = A(BB^{-1})A^{-1} = A^{-1}IA = I$$

So by definition the inverse of  $AB$ , which is denoted by  $(AB)^{-1}$ , is  $B^{-1}A^{-1}$ . That is,

$$(AB)^{-1} = B^{-1}A^{-1}.$$

**Question 9. (16 pts)**

Recall that two vectors  $v, w \in \mathbb{R}^n$  are said to be orthogonal if their dot product is zero, that is,  $v \cdot w = 0$ .

- (a) Let  $u_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ ,  $u_2 = \begin{bmatrix} +1 \\ 0 \\ -1 \end{bmatrix}$  and  $u_3 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$  in  $\mathbb{R}^3$ . Determine whether  $u_1$ ,  $u_2$  and  $u_3$  are mutually orthogonal.

**Solution:** A straightforward calculation shows that  $u_1$ ,  $u_2$  and  $u_3$  are mutually orthogonal.

- (b) Suppose  $v$  and  $w$  are both nonzero vectors in  $\mathbb{R}^n$ . Show that if  $v \cdot w = 0$ , then  $v$  and  $w$  are linearly independent. (Hint: For any linear combination of  $v$  and  $w$ , take the dot product of this linear combination with  $v$  (respectively  $w$ ). What do you see?)

**Solution:** Suppose we have a linear combination

$$a_1v + a_2w = 0.$$

Then we need to show that  $a_1 = a_2 = 0$ .

Indeed, consider the dot product

$$0 = (a_1v + a_2w) \cdot v = a_1\|v\|^2 + 0 = a_1\|v\|^2$$

But  $\|v\| \neq 0$ . Therefore  $a_1 = 0$ .

Similarly,

$$0 = (a_1v + a_2w) \cdot w = 0 + a_2\|w\|^2 + 0 = a_2\|w\|^2$$

shows that  $a_2 = 0$ .

So  $v$  and  $w$  are linearly independent.

- (c) Now suppose nonzero vectors  $v_1, v_2$  and  $v_3$  are mutually orthogonal in  $\mathbb{R}^n$ . Show that the set  $\{v_1, v_2, v_3\}$  is linearly independent. (Hint: the same idea from part (b) applies.)

**Solution:** Suppose we have a linear combination

$$a_1v_1 + a_2v_2 + a_3v_3 = 0.$$

Then we need to show that  $a_1 = a_2 = a_3 = 0$ .

Consider the dot product

$$0 = (a_1v_1 + a_2v_2 + a_3v_3) \cdot v_1 = a_1\|v_1\|^2$$

But  $\|v_1\| \neq 0$ . Therefore  $a_1 = 0$ .

Similarly, by taking the dot product of  $a_1v_1 + a_2v_2 + a_3v_3$  with  $v_2$  and  $v_3$  respectively, we have  $a_2 = a_3 = 0$ .

Therefore, the set  $\{v_1, v_2, v_3\}$  is linearly independent.

- (d) Use either the previous parts or your other favorite method to determine whether

$$u_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, u_2 = \begin{bmatrix} +1 \\ 0 \\ -1 \end{bmatrix} \text{ and } u_3 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \text{ form a basis of } \mathbb{R}^3.$$

**Solution:** From part (a), we know that  $u_1, u_2$  and  $u_3$  are mutually orthogonal and are nonzero vectors.

By part (c), we know  $u_1, u_2$  and  $u_3$  are linearly independent.

Since  $\dim \mathbb{R}^3 = 3$ , we see that  $u_1, u_2$  and  $u_3$  form a basis of  $\mathbb{R}^3$ .